

Engineering Village 开展工程领域研究的首选方案

Ei Compendex

李海舰 博士 爱思唯尔资深培训师

2024





内容目录:

1. El数据库简介

- 2. El数据库文献检索过程
- 3. EI数据库在工科文献调研中的应用
- 4. 索引结果在科研及投稿上的分析与利用
- 5. 科研机构在工程领域上的科研产出分析









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- 应用物理学,包括光学
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数据库介绍	教学课件: El 《El》(工程索引, Engineering Index)创刊于1884年,是美国工程信息公司出版的著名工程技术类综合性检索工具。目前, Engineering Village 平台集成了多个数据库,其中核心数据库为El Compendex。 El Compendex选用世界上工程技术类期刊5600多种期刊、行业杂志、会议录(22%)和技术报告的参考资料及摘要;收录文献几 乎涉及工程技术各个领域。如石油、应用物理、电子、自动控制、机械制造、土木、化学和工艺、材料等学科。它具有综合性 强、资料来源广、地理覆盖面广、报道量大、报道质量高、权威性强等特点。 Ei Compendex是全世界最早最全面的工程文摘来源,收录自1969年以来的期刊、会议录、科技报告等文摘信息。 收录年限: 1969年-至今
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Abstract

Intelligent-PID (i-PID) control proposed by Fliess is a simple control algorithm. The controller is designed based on ultra-local model, and consisted of PID type controller and derivatives of reference signal and controlled variables. Authors have considered discrete i-PID controller and its properties, and one of the result was that PD controller was sufficient in discrete time domain. In discrete i-PID controller, PD type controller is still required to ensure convergence of controlled error to zero, and PD type parameters affects convergence property, fast-response property and stability. In this paper, predictive functional control (PFC) based on an ultra-local model is proposed. By introducing of PFC, controlled variable converge to reference value without PD type controller. User-specified parameters of the proposed controller is smaller than the conventional i-PID controller. Characteristics of the proposed curvel are compared with discrete i-PID controller by numerical examples. (© 2024 Wiley Periodicals LLC.



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Compendex • Journal article (JA)

Design of a model-free controller based on predictive functional control

Electronics and Communications in Japan, Volume 107, Issue 1, March 2024

Ashida, Yoichiro [1] 🖾 ; Katayama, Masaru [1]

Corresponding author: Ashida, Yoichiro 🖂

Author affiliation:

[1] Department of Electrical Engineering and Computer Science, National Institute of Technology, Matsue College, Matsue, Japan

Abstract

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State Key Laboratory Of Organic Geochemistry, (211						
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discrete i-PID controller, PD type controller is still required to ensure convergence of controlled error to zero, and PD type parameters affects convergence property, fast-response property and stability. In this paper, predictive functional control (PFC) based on an ultra-local model is proposed. By introducing of PFC, controlled variable converge to reference value without PD type controller. User-specified parameters of the proposed controller is somaller than the conventional I-PID controller. Characteristics of the proposed controller are compared with discrete i-PID controller by numerical examples. © 2024 Wiley Periodicals LLC.

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1. Design of a model-free controller based on predictive functional control

Accession number: 20240815612857

Authors: Ashida, Yoichiro (1); Katayama, Masaru (1)

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Number of references: 10

Main heading: Controllers

Controlled terms: Electric control equipment - Proportional control systems - Three term control systems Uncontrolled terms: Controlled variables - Data-driven control - Intelligent PID control - Local model - Madel free controller - PID controllers - PID-type controller - Predictive functional control - Simpler+ - Ultro-local model Classification code: 704.2 Electric Equipment - 7311 Control Systems - 732.1 Control Equipment

DOI: 10.1002/ecj.12442

Compendex references: YES Database: Compendex

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Electric batteries	Battery management systems	Automotive batteries			
	Battery storage	Battery Pack			
	Charging (batteries)	Flow batteries			
	Charging time	Lead acid batteries			
	Electric bikes	Lithium batteries		Reset form	Q
	Electrolysis	Lithium sulfur batteries			
	Fast charging (Batteries)	Metal-air batteries			
	Light electric vehicles	Nickel cadmium batteries			
	Plug-in electric vehicles	Nickel metal hydride			
	Plug-in hybrid vehicles	Datteries			
	State of charge	Solid-State Batteries			
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一、文献收集重点-文献调研阶段





此页引自清华大学图书馆钱俊雯《开题与立项前的文献调研概述(理工类)》

- 二、先看综述性论文,再看研究论文。
- 特点:综合性、扼要性和评价性,参考文献多。应作为"起步文献"加以参考利用。

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3. 🗌 Toward reliable off road autonomous vehicles operating in challenging environments

Kelly, Alonzo (Robotics Institute, Carnegie Mellon University); Stentz, Anthony; Amidi, Omead; Bode, Mike; Bradley, David; Diaz-Calderon, Antonio; Happold, Mike; Herman, Herman; Mandelbaum, Robert; Pilarski, Tom; Rander, Pete; Thayer, Scott; Vallidis, Nick; Warner, Randy Source: International Journal of Robotics Research, v 25, n 5-6, p 449-483, May/June 2006 Database: Compendex Document type: Conference article (CA) Show preview \checkmark Cited by in Scopus [18]) Eul text Z BUT Holding Z SEX Z

4. Real-time motion planning for agile autonomous vehicles



Frazzoli, Emilio (University of Illinois at UC, Dept. of Aero./Astronautical Eng., 321b Talbot Laboratory, 104 S. Wright Street, Urbana, IL 61801, United States); Dahleh, Munther A.; Feron, Eric Source: Journal of Guidance, Control, and Dynamics, v 25, n 1, p 116-129, January/February 2002
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Thanks for listening!

(Q&A)

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